

**Topic of this homework:** Fundamental theorem of algebra, polynomials, analytic functions, convolution, analytic geometry, composition, intersection.

Deliverable: Answers to problems

*Note: The term ‘analytic’ is used in two different ways. (1) An analytic function is a function that may be expressed as a locally convergent power series; (2) analytic geometry refers to geometry using a coordinate system.*

## 1 Polynomials and the fundamental theorem of algebra (FTA)

A polynomial of degree  $N$  is defined as

$$P_N(x) = a_0 + a_1x + a_2x^2 \cdots a_Nx^N$$

1. How many coefficients  $a_n$  does a polynomial of degree  $N$  have?
2. How many roots does  $P_N(x)$  have?
3. The *fundamental theorem of algebra* (FTA)
  - (a) State the FTA.
  - (b) Using the FTA, *prove* your answer to question (2) above.
4. Consider the polynomial function  $P_2(x) = 1 + x^2$  of degree  $N = 2$ , and the related function  $F(x) = 1/P_2(x)$ .
  - (a) What are the roots (e.g. ‘zeros’)  $x_{\pm}$  of  $P_2(x)$ ?
  - (b)  $F(x)$  may be expressed as  $(A, B, x_{\pm} \in \mathbb{C})$

$$F(x) = \frac{A}{x - x_+} + \frac{B}{x - x_-}, \quad (1)$$

where  $x_{\pm}$  are the roots (zeros) of  $P_2(x)$ , which become the *poles* of  $F(x)$ , and  $A, B$  are the *residues*. The expression for  $F(x)$  is sometimes called a ‘partial fraction expansion’ or ‘residue expansion,’ and it appears in many engineering applications.

- i. Find  $A, B \in \mathbb{C}$  in terms of the roots  $x_{\pm}$  of  $P_2(x)$ .
  - ii. Verify your answers for  $A, B$  by showing that this expression for  $F(x)$  is indeed equal to  $1/P_2(x)$ .
- (c) The *poles* of a function  $G(x)$  are defined as values  $x_p$  where  $G(x_p) \rightarrow \infty$ ; the *zeros* are defined as values  $x_z$  where  $G(x_z) = 0$ .
- Hint: Do not forget to consider  $f(x)$  as  $x \rightarrow \pm\infty$*
- i. Give the values of the poles and zeros of  $P_2(x)$ .
  - ii. Give the values of the poles and zeros of  $F(x) = 1/P_2(x)$ .

## 2 Analytic functions

*Analytic functions* are defined by infinite (power) series. The function  $f(x)$  is analytic at any value of  $x = x_0$  where there exists a convergent power series  $P(x) = \sum_{n=0}^{\infty} a_n x^n$  such that  $P(x_0) = f(x_0)$ . The local power series for  $f(x)$  near  $x = x_0$  is often obtained by finding the *Taylor series*:

$$\begin{aligned} f(x) &\approx f(x_0) + \left. \frac{df}{dx} \right|_{x=x_0} (x - x_0) + \frac{1}{2!} \left. \frac{d^2 f}{dx^2} \right|_{x=x_0} (x - x_0)^2 + \dots \\ &= \sum_{n=0}^{\infty} \frac{1}{n!} \left. \frac{d^n}{dx^n} f(x) \right|_{x=x_0} (x - x_0)^n \end{aligned}$$

The point  $x = x_0$  is called the series expansion point.

When the expansion point is at  $x_0 = 0$ , the series is denoted a *MacLaurin series*. Two classic examples are the *geometric series*<sup>1</sup>

$$\frac{1}{1-x} = 1 + x + x^2 + x^3 + \dots = \sum_{n=0}^{\infty} x^n \quad (1)$$

and the exponential function

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} \dots = \sum_{n=0}^{\infty} \frac{x^n}{n!}. \quad (2)$$

These expressions may both be derived as the Taylor (MacLaurin) series about  $x = 0$ .

### 1. The geometric series

- What is the region of convergence (ROC) for the power series of  $1/(1-x)$  given above (e.g. where does the power series  $P(x)$  converge to the function value  $f(x)$ )? State your answer as a condition on  $x$ . *Hint: What happens to the power series when  $x > 1$ ?*
- How does the ROC relate to the location of the pole of  $1/(1-x)$ ?
- Assuming  $x$  is in the ROC, prove that the geometric series correctly represents  $1/(1-x)$  by multiplying both sides of Eq. 1 by  $(1-x)$ .
- Use the geometric series to study the degree  $N$  polynomial (It is very important to note that all the coefficients of this polynomial are 1)

$$P_N(x) = 1 + x + x^2 + \dots + x^N = \sum_{n=0}^N x^n. \quad (3)$$

#### i. Prove that

$$P_N(x) = \frac{1 - x^{N+1}}{1 - x} \quad (4)$$

- How many poles does  $P_N(x)$  have? Where are they?
  - How many zeros does  $P_N(x)$  have? Where are they?
  - Explain why Eq. 3 and 4 have different numbers of poles and zeros.
- (e) Is the function  $1/(1-x)$  analytic outside of the ROC stated in part (a)? *Hint: Can it be represented by a different power series outside this ROC?*

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<sup>1</sup>The geometric series is *not* defined as the function  $1/(1-x)$ , it is defined as the series  $1 + r + r^2 + r^3 + \dots$ , such that the ratio of consecutive terms is  $r$ .

## 2. The exponential series

- What is the region of convergence (ROC) for the exponential series given above (e.g. where does the power series  $P(x)$  converge to the function value  $f(x)$ )?
- Let  $x = j$  in Eq. 2, and write out the series expansion of  $e^x$  in terms of its real and imaginary parts.
- Let  $x = j\theta$  in Eq. 2, and write out the series expansion of  $e^x$  in terms of its real and imaginary parts. How does your result relate to Euler's identity ( $e^{j\theta} = \cos(\theta) + j \sin(\theta)$ )?

## 3 Inverse analytic functions and composition

It may be surprising, but every analytic function has an inverse function. Starting from the function ( $x, y \in \mathbb{C}$ )

$$y(x) = \frac{1}{1-x}$$

the inverse is

$$x = \frac{y-1}{y} = 1 - \frac{1}{y}.$$

- Considering the inverse function described above
  - Where are the poles and zeros of  $x(y)$ ?
  - Where (for what condition on  $y$ ) is  $x(y)$  analytic?
- Considering the exponential function  $z(x) = e^x$  ( $x, z \in \mathbb{C}$ )
  - Find the inverse  $x(z)$ .
  - Where are the poles and zeros of  $x(z)$ ?
- Compose these two functions  $(y \circ z)(x)$ 
  - Give the expression for  $(y \circ z)(x) = y(z(x))$ .
  - Where are the poles and zeros of  $(y \circ z)(x)$ ?
  - Where (for what condition on  $x$ ) is  $(y \circ z)(x)$  analytic?

## 4 Convolution

Multiplying two polynomials, when they are short or simple, is not demanding. However if they have many terms, it can become tedious. For example, multiplying two  $10^{th}$  degree polynomials is not something one would want to do every day.

An alternative is a method called convolution, as described in Lecture 13.

### 1. Convolution of sequences

Practice convolution (by hand!!) using a few simple examples. Show your work!!! You may check your solution using Matlab.

- Convolve the sequence  $[0 \ 1 \ 1 \ 1 \ 1]$  with itself.
- Convolve  $[1 \ 1]$  with itself, then convolve the result with  $[1 \ 1]$  again (e.g., calculate  $[1, 1] \star [1, 1] \star [1, 1]$ ).

## 2. Multiplication of polynomials

In class, it was shown that multiplying two polynomials is the same as convolving their coefficients. Consider

$$\begin{aligned}f(x) &= x^3 + 3x^2 + 3x + 1 \\g(x) &= x^3 + 2x^2 + x + 2\end{aligned}$$

In Matlab, compute  $h(x) = f(x) \cdot g(x)$  two ways using (a) the commands `roots` and `poly`, and (b) the convolution command `conv`. Confirm that both methods give the same result. That is, compute the convolution  $[1, 3, 3, 1] \star [1, 2, 1, 2]$ .

What is  $h(x)$ ?

## 5 Intersection and analytic geometry

To find the Euclid's formula, it was necessary to study the intersection of a circle and a secant line. Consider the unit circle of radius 1, centered at  $(x, y) = (0, 0)$

$$x^2 + y^2 = 1$$

and the line through  $(-1, 0)$

$$y = t(x + 1).$$

If  $0 < t < 1$ , the line intersects the circle at a second point  $(+x, +y)$  in the positive  $x, y$  quadrant.

1. Draw the circle and the line, given a positive slope  $0 < t < 1$ .
2. Substitute  $y = t(x + 1)$  (the line equation) into the equation for the circle, and solve for  $x(t)$ .  
*Hint: Because the line intersects the circle at two points, you will get two solutions for  $x$ . One of these solutions is the trivial solution  $x = -1$ .*
3. Substitute the  $x(t)$  you found back into the line equation, and solve for  $y(t)$ .
4. Let  $t = q/p$  be a rational number, where  $p$  and  $q$  are integers. Find  $x(p, q)$  and  $y(p, q)$ .
5. Substitute  $x(p, q)$  and  $y(p, q)$  into the equation for the circle, and show how Euclid's formula for the Pythagorean triples is generated.

## 6 Newton's root-finding method (Extra credit)

Newton used the iteration<sup>2</sup>

$$x_{n+1} = x_n - \frac{P_N(x_n)}{P'_N(x_n)}$$

to find roots of the polynomial  $P_N(x)$ . Here  $P'_N(x) = dP_N(x)/dx$ . This relation may be explored as a graph, which puts Newton's method in the realm of analytic geometry. The function  $P'_N(x)$  is the slope of the polynomial  $P_N(x)$  at  $x_n$ . The value of  $x_n$  is the estimate of the root after  $n$  iterations.  $x_0$  is the initial guess.

Example: When the polynomial is  $P_2 = 1 - x^2$ , so  $P'_2(x) = -2x$  Newton's iteration becomes

$$x_{n+1} = x_n + \frac{1 - x_n^2}{2x_n}.$$

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<sup>2</sup>[https://en.wikipedia.org/wiki/Newton's\\_method](https://en.wikipedia.org/wiki/Newton's_method)

To start the iteration ( $n = 0$ ) we need an initial guess for  $x_0$ , which is a “best guess” of where the root will be. If we let  $x_0 = 1/2$ , then

$$x_1 = x_0 - \frac{1 - x_0^2}{2x_0} = x_0 + \frac{1}{2}(x_0 - 1/x_0).$$

1. Let  $P_2(x) = 1 - x^2$ , and  $x_0 = 1/2$ . Draw a graph describing the first step of the iteration.
2. Calculate  $x_1$  and  $x_2$ . What number is the algorithm approaching? Is it a root of  $P_2$ ?
3. Write a Matlab script to check your answer for part (a).
  - (a) For  $n = 4$ , what is the absolute difference between the root and the estimate,  $|x_r - x_4|$ ?
  - (b) What happens if  $x_0 = -1/2$ ?
4. Does Newton’s method work for  $P_2(x) = 1 + x^2$ ? Why?<sup>3</sup> Hint: What are the roots in this case?
5. What if you let  $x_0 = (1 + j)/2$  for the case of  $P_2(x) = 1 + x^2$ ?

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<sup>3</sup>[https://en.wikipedia.org/wiki/Newton's\\_method#Complex\\_functions](https://en.wikipedia.org/wiki/Newton's_method#Complex_functions)