

3.3 Problems DE-3

3.3.1 Topics of this homework: Brune impedance

lattice transmission line analysis

3.3.2 Brune Impedance

Problem # 1: Residue form

A Brune impedance is defined as the ratio of the force $F(s)$ to the flow $V(s)$ and may be expressed in residue form as

$$Z(s) = c_0 + \sum_{k=1}^K \frac{c_k}{s - s_k} = \frac{N(s)}{D(s)} \quad (\text{DE-3.1})$$

with

$$D(s) = \prod_{k=1}^K (s - s_k) \quad \text{and} \quad c_k = \lim_{s \rightarrow s_k} (s - s_k) D(s) = \prod_{n'=1}^{K-1} (s - s_{n'}).$$

The prime on the index n' means that $n = k$ is not included in the product.

– 1.1: Find the Laplace transform (\mathcal{LT}) of a (1) spring, (2) dashpot, and (3) mass.

Express these in terms of the force $F(s)$ and the velocity $V(s)$, along with the electrical equivalent impedance: (1) Hooke's law $f(t) = Kx(t)$, (2) dashpot resistance $f(t) = Rv(t)$, and (3) Newton's law for mass $f(t) = Mdv(t)/dt$. **Sol:**

1. Hooke's Law $f(t) = Kx(t)$. Taking the \mathcal{LT} gives

$$F(s) = KX(s) = KV(s)/s \leftrightarrow f(t) = Ku(t) \star v(t) = K \int^t v(t),$$

since

$$v(t) = \frac{d}{dt}x(t) \leftrightarrow V(s) = sX(s).$$

Thus the impedance of the spring is

$$Z_s(s) = \frac{K}{s} \leftrightarrow z(t) = Ku(t),$$

which is analogous to the impedance of an electrical capacitor. The relationship may be made tighter by specifying the compliance of the spring as $C = 1/K$.

2. Dashpot resistance $f(t) = Rv(t)$. From the \mathcal{LT} this becomes

$$F(s) = RV(s)$$

and the impedance of the dashpot is then

$$Z_r = R \leftrightarrow R\delta(t),$$

analogous to that of an electrical resistor.

3. Newton's law for mass $f(t) = Mdv(t)/dt$. Taking the \mathcal{LT} gives

$$f(t) = M \frac{d}{dt}v(t) \leftrightarrow F(s) = M sV(s),$$

thus

$$Z_m(s) = sM \leftrightarrow M \frac{d}{dt},$$

analogous to an electrical inductor.

■

– 1.2: Take the Laplace transform (\mathcal{LT}) of Eq. DE-3.2 and find the total impedance $Z(s)$ of the mechanical circuit.

$$M \frac{d^2}{dt^2} x(t) + R \frac{d}{dt} x(t) + Kx(t) = f(t) \leftrightarrow (Ms^2 + Rs + K)X(s) = F(s). \quad (\text{DE-3.2})$$

Sol: From the properties of the \mathcal{LT} that $dx/dt \leftrightarrow sX(s)$, we find

$$f(t) \leftrightarrow F(s) = Ms^2X(s) + RsX(s) + KX(s).$$

In terms of velocity this is $(Ms + R + K/s)V(s) = F(s)$. Thus the circuit impedance is

$$z(t) \leftrightarrow Z(s) = \frac{F}{V} = \frac{K + Rs + Ms^2}{s}.$$

■

– 1.3: What are $N(s)$ and $D(s)$ (see Eq. DE-3.1)?

Sol: $D(s) = s$ and $N(s) = K + Rs + Ms^2$. ■

– 1.4: Assume that $M = R = K = 1$ and find the residue form of the admittance $Y(s) = 1/Z(s)$ (see Eq. DE-3.1) in terms of the roots s_{\pm} . Hint: Check your answer with Octave's/Matlab's residue command.

Sol: First find the roots of the numerator of $Z(s)$ (the denominator of $Y(s)$):

$$s_{\pm}^2 + s_{\pm} + 1 = (s_{\pm} + 1/2)^2 + 3/4 = 0,$$

which is

$$s_{\pm} = \frac{-1 \pm j\sqrt{3}}{2}.$$

Second form a partial fraction expansion

$$\frac{s}{1 + s + s^2} = c_0 + \frac{c_+}{s - s_+} + \frac{c_-}{s - s_-} = \frac{s(c_+ + c_-) - (c_+s_- + c_-s_+)}{1 + s + s^2}.$$

Comparing the two sides shows that $c_0 = 0$. We also have two equations for the residues $c_+ + c_- = 1$ and $c_+s_- + c_-s_+ = 0$. The best way to solve this is to set up a matrix relation and take the inverse

$$\begin{bmatrix} 1 & 1 \\ s_- & s_+ \end{bmatrix} \begin{bmatrix} c_+ \\ c_- \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{thus:} \quad \begin{bmatrix} c_+ \\ c_- \end{bmatrix} = \frac{1}{s_+ - s_-} \begin{bmatrix} s_+ & -1 \\ -s_- & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix},$$

which gives $c_{\pm} = \pm \frac{s_{\pm}}{s_+ - s_-}$. The denominator is $s_+ - s_- = j\sqrt{3}$ and the numerator is $\pm 1 + j\sqrt{3}$. Thus

$$c_{\pm} = \pm \frac{s_{\pm}}{s_+ - s_-} = \frac{1}{2} \left(1 \pm \frac{j}{\sqrt{3}} \right).$$

As always, finding the coefficients is always the most difficult part. Using 2x2 matrix algebra automates the process. Always check your final result as correct. ■

– 1.5: By applying Eq. NS-3.3 (page 135), find the inverse Laplace transform (\mathcal{LT}^{-1}). Use the residue form of the expression that you derived in question 1.4.

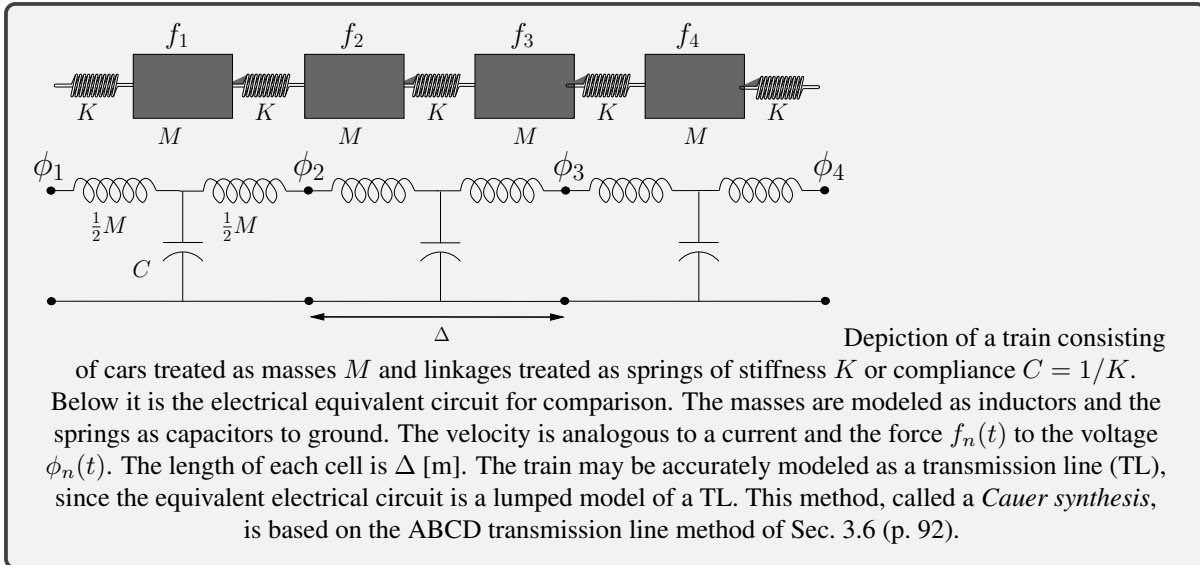
Sol:

$$z(t) = \frac{1}{2\pi j} \oint_C Z(s) e^{st} ds.$$

where C is the Laplace contour which encloses the entire left-half s plane. Applying the CRT

$$z(t) = c_+ e^{s_+ t} + c_- e^{s_- t}.$$

where $s_{\pm} = -1/2 \pm j\sqrt{3}/2$ and $c_{\pm} = 1/2 \pm j/(2\sqrt{3})$. ■



3.3.3 Transmission-line analysis

Problem # 2: (14 pts) Train-mission-line We wish to model the dynamics of a freight train that has N such cars and study the velocity transfer function under various load conditions.

As shown in Fig. 4.8.2, the train model consists of masses connected by springs.

Problem # 3: Transfer functions

Use the ABCD method (see the discussion in Appendix B.3, p. 212) to find the matrix representation of the system of Fig. 4.8.2. Define the force on the n th train car $f_n(t) \leftrightarrow F_n(\omega)$ and the velocity $v_n(t) \leftrightarrow V_n(\omega)$. Break the model into cells consisting of three elements: a series inductor representing half the mass ($M/2$), a shunt capacitor representing the spring ($C = 1/K$), and another series inductor representing half the mass ($L = M/2$), transforming the model into a cascade of symmetric ($\mathcal{A} = \mathcal{D}$) identical cell matrices $\mathcal{T}(s)$.

– 3.1: Find the elements of the ABCD matrix \mathcal{T} for the single cell that relate the input node 1 to output node 2

$$\begin{bmatrix} F \\ V \end{bmatrix}_1 = \mathcal{T} \begin{bmatrix} F(\omega) \\ -V(\omega) \end{bmatrix}_2. \quad (\text{DE-3.3})$$

Sol:

$$\begin{aligned} \mathcal{T} &= \begin{bmatrix} 1 & sM/2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ sC & 1 \end{bmatrix} \begin{bmatrix} 1 & sM/2 \\ 0 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 + s^2MC/2 & (sM)(1 + s^2MC/4) \\ sC & 1 + s^2MC/2 \end{bmatrix} \end{aligned} \quad (\text{DE-3.4a})$$

■

– 3.2: Express each element of $\mathcal{T}(s)$ in terms of the complex Nyquist ratio $s/s_c < 1$ ($s = 2\pi j f$, $s_c = 2\pi j f_c$). The Nyquist wavelength sampling condition is $\lambda_c > 2\Delta$. It says the critical wavelength $\lambda_c > 2\Delta$.^a It says the critical wavelength $\lambda_c > 2\Delta$. Namely it is defined in terms the minimum number of cells 2Δ , per minimum wavelength λ_c .

The Nyquist wavelength sampling theorem says that there are at least two cars per wavelength.

Proof: From the figure, the distance between cars $\Delta = c_o T_o$ [m], where

$$c_o = \frac{1}{\sqrt{MC}} \quad [\text{m/s}].$$

The cutoff frequency obeys $f_c \lambda_c = c_o$. The Nyquist critical wavelength is $\lambda_c = c_o/f_c > 2\Delta$. Therefore the Nyquist sampling condition is

$$f < f_c \equiv \frac{c_o}{\lambda_c} = \frac{c_o}{2\Delta} = \frac{1}{2\Delta\sqrt{MC}} \quad [\text{rad/sec}]. \quad (\text{DE-3.5})$$

Finally, $s_c = j2\pi f_c$.

Sol: The solution is a repeat what is summarized above: the system in Fig. 4.8.2 represents a transmission line having a wave speed of $c_o = 1/\sqrt{MC}$ and characteristic impedance $r_o = \sqrt{M/C}$. Each cell, composed of 2 masses M connected by one spring K , has length Δ .

We wish to define the Nyquist frequency f_c such that the wavelength $\lambda > 2\Delta$, where Δ is the cell length. Using the formula for the wavelength in terms of the wave velocity and frequency we find

$$\lambda = c_o/f_c = 2\Delta,$$

thus we conclude that

$$f < f_c = \frac{c_o}{2\Delta} = \frac{1}{2\Delta\sqrt{MC}}. \quad (\text{DE-3.6})$$

If we wish to have the system be accurate for a given frequency we may make the cell length Δ smaller, while keeping the velocity constant (MC is held constant). Thus the characteristic resistance [ohms/unit length] r_o must change as $f_c \rightarrow \infty$ and $\Delta \rightarrow 0$. We can either let $M \rightarrow \infty$ and $C \rightarrow 0$ (their product remains constant), or the other way around. In one case $r_o \rightarrow \infty$ and in the other case it goes to 0. ■

^aThe history of this relation has been traced back to 1841, as discussed by (Brillouin, 1953, Chap. I,II, Eq. 4.7).

– 3.3: Use the property of the Nyquist sampling frequency $\omega < \omega_c$ (Eq. DE-3.4) to remove higher order powers of frequency

$$1 + \left(\frac{s}{s_c}\right)^2 \approx 1 \quad (\text{DE-3.7})$$

to determine a band-limited approximation of $\mathcal{T}(s)$.

Sol:

$$\mathcal{T} = \begin{bmatrix} 1 + 2(s/s_c)^2 & sM(1 + (s/s_c)^2) \\ sC & 1 + 2(s/s_c)^2 \end{bmatrix} \\ \approx \begin{bmatrix} 1 & sM \\ sC & 1 \end{bmatrix}$$

The approximation is highly accurate below the Nyquist cutoff frequency $s < s_c$. Given any desired frequency f , we can always make the cell size Δ smaller by decreasing M and C , while keeping $f < f_c$ and the cell velocity constant ($c_o = 1/\sqrt{MC}$). Thus the Nyquist condition represents a computational bound, not a physical limitation. ■

Problem # 4: (4 pts) Now consider the cascade of N such $\mathcal{T}(s)$ matrices and perform an eigenanalysis.

– 4.1: (4 pts) Find the eigenvalues and eigenvectors of $\mathcal{T}(s)$ as functions of s/s_c .

Sol: Matrix $\mathcal{T}(s)$ has eigenvalues

$$\lambda_{\pm} = 1 \mp 2s/s_c \approx e^{\pm 2s/s_c} = e^{\mp s T_c}.$$

From this we can interpret the eigenvalues as the cell delay $T_c = 2/s_c$.

The corresponding unnormalized eigenvectors are

$$\mathbf{E}_{\pm} = \begin{bmatrix} \mp \sqrt{M/C} \\ 1 \end{bmatrix},$$

where the characteristic impedance defined is $r_o = \sqrt{M/C}$. ■

Problem # 5: (14 pts) Find the velocity transferfunction $H_{12}(s) = V_2/V_1|_{F_2=0}$.

– 5.1: (3 pts) Assuming that $N = 2$ and $F_2 = 0$ (two half-mass problem), find the transfer function $H(s) \equiv V_2/V_1$. From the results of the \mathcal{T} matrix, find

$$H_{21}(s) = \left. \frac{V_2}{V_1} \right|_{F_2=0}$$

Express H_{12} in terms of a residue expansion.

Sol: From Eq. DE-3.4a, $V_1 = sCF_2 - (s^2MC/2 + 1)V_2$. Since $F_2 = 0$

$$\frac{V_2}{V_1} = \frac{-1}{s^2MC/2 + 1} = \left(\frac{c_+}{s - s_+} + \frac{c_-}{s - s_-} \right)$$

having eigenfrequencies $s_{\pm} = \pm j\sqrt{\frac{2}{2MC}} = \pm s_c$ and residues $c_{\pm} = \pm j/\sqrt{2MC} = \pm s_c$. ■

– 5.2: (2 pts) Find $h_{21}(t) \leftrightarrow H_{21}(s)$.

Sol:

$$h(t) = \oint_{\sigma_0 - j\infty}^{\sigma_0 + j\infty} \frac{e^{st}}{s^2MC/2 + 1} \frac{ds}{2\pi j} = c_+ e^{-s_+ t} u(t) + c_- e^{-s_- t} u(t).$$

The integral follows from the Cauchy Residue theorem (CRT). ■

– 5.3: (2 pts) What is the input impedance $Z_2 = F_2/V_2$, assuming $F_3 = -r_0 V_3$?

Sol: Starting from Eq. DE-3.4a find Z_2

$$Z_2(s) = \frac{F_2}{V_2} = T \begin{bmatrix} F \\ -V \end{bmatrix}_2 = \frac{-(1 + s^2CM/2)r_0 \cancel{Y_2} - sM(1 + s^2CM/4)\cancel{Y_2}}{-sCr_0 \cancel{Y_2} - (1 + s^2CM/2)\cancel{Y_2}}$$

■

– 5.4: (5 pts) Simplify the expression for Z_2 as follows:

1. Assuming the characteristic impedance $r_0 = \sqrt{M/C}$,
2. terminate the system in r_0 : $F_2 = -r_0 V_2$ (i.e., $-V_2$ cancels).
3. Assume higher-order frequency terms are less than 1 ($|s/s_c| < 1$).
4. Let the number of cells $N \rightarrow \infty$. Thus $|s/s_c|^N = 0$.

When a transmission line is terminated in its characteristic impedance r_0 , the input impedance $Z_1(s) = r_0$. Thus, when we simplify the expression for $\mathcal{T}(s)$, it should be equal to r_0 . Show that this is true for this setup.

Sol: Applying the Nyquist approximation (i.e., ignore second order frequency terms $(s/s_c)^2 \approx 0$)

$$\begin{aligned} Z_1(s) &= \frac{r_0(1 + \overset{0}{s^2 CM/2}) + sM(1 + \overset{0}{s^2 CM/4})}{r_0 sC + (1 + \overset{0}{s^2 CM/2})} \\ &\approx \frac{r_0 + sM}{1 + r_0 sC} = \frac{MC}{MC} \cdot \frac{r_0 + sM}{1 + r_0 sC} = \frac{M}{C} \cdot \frac{r_0 C + sMC}{M + r_0 sMC} = r_0^2 \frac{r_0 C + s/s_c}{M + r_0 s/s_c} \\ &\approx r_0^2 \frac{r_0 C + \overset{0}{s/s_c}}{M + r_0 \overset{0}{s/s_c}} = r_0^3 \frac{C}{M} \\ &= r_0. \end{aligned}$$

We conclude that below the Nyquist cutoff frequency, as $N \rightarrow \infty$ the system equals a transmission line terminated by its characteristic impedance thus $Z_1(s) = r_0$. ■

– 5.5: (1 pts) State the ABCD matrix relationship between the first and N th nodes in terms of the cell matrix. Write out the transfer function for one cell, H_{21} .

Sol:

$$\mathcal{T} = \begin{bmatrix} \mathcal{A} & \mathcal{B} \\ \mathcal{C} & \mathcal{D} \end{bmatrix}$$

Now use the formulae for the eigenvalues and vectors to obtain \mathcal{T} for $N = 1$:

$$\mathcal{T} = E\Lambda E^{-1} = E \begin{bmatrix} \lambda_+ & 0 \\ 0 & \lambda_- \end{bmatrix} E^{-1}.$$

■

– 5.6: (1 pts) What is the velocity transfer function $H_{N1} = \frac{V_N}{V_1}$?

Sol:

$$\begin{bmatrix} F_1 \\ V_1 \end{bmatrix} = \mathcal{T}^N \begin{bmatrix} F_N(\omega) \\ -V_N(\omega) \end{bmatrix}$$

along with the eigenvalue expansion

$$\mathcal{T}^N = E\Lambda^N E^{-1} = E \begin{bmatrix} \lambda_+^N & 0 \\ 0 & \lambda_-^N \end{bmatrix} E^{-1}.$$

where $\lambda_{\pm}^N = e^{\mp sNT_o}$. Recall that NT_o is the one way delay.

We conclude that as we add more cells, the delay linearly increases with N , since each eigenvalue represents the delay of one cell, and delay adds. ■

