Chapter 5 – The Acoustic Wave Equation and Simple Solutions

(5.1) In this chapter we are going to develop a simple linear wave equation for sound propagation in fluids (1D). In reality the acoustic wave equation is nonlinear and therefore more complicated than what we will look at in this chapter. However, in most common applications, the linear approximation to the wave equation is a good model. Only when sound waves have high enough amplitude do nonlinear effects show themselves.

What is an acoustic wave? It is essentially a pressure change. A local pressure change causes immediate fluid to compress which in turn causes additional pressure changes. This leads to the propagation of an acoustic wave.

Before we derive the wave equation, let’s cover a few definitions and concepts.

Generation → Transducer (piston for example) creates a particle displacement (which in turn has an associated pressure and density change). This change affects the immediately adjacent region, etc., so that the disturbance (wave) propagates.

Uniform plane wave → common phase and amplitude in a plane ⊥ direction of propagation.

Particle We will talk a lot about particle displacement. It is defined in terms of continuum mechanics. A particle contains many molecules (large enough to be considered as a continuous medium) but its dimensions are small compared to the distances for significant changes in the acoustic parameters (for example, small compared to $\lambda$ or small enough to consider acoustic variables constant throughout particle volume).

Parameters
- acoustic pressure
- particle displacement
- particle velocity
- particle acceleration
- density changes
- velocity potential

\[
p = \rho \frac{\partial^2 \xi}{\partial t^2}
\]

\[
\begin{align*}
\bar{r} &= x \hat{x} + y \hat{y} + z \hat{z} \\
\bar{\xi} &= \xi_x \hat{x} + \xi_y \hat{y} + \xi_z \hat{z} \\
\bar{u} &= \frac{\partial \bar{\xi}}{\partial t} \\
\bar{\rho} &= \rho
\end{align*}
\]

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condensation
\[ s = \frac{\rho - \rho_0}{\rho_0} \]
undisturbed (equilibrium) density

acoustic pressure
\[ p = P - P_0 \]
instantaneous undisturbed (ambient pressure) pressures

Three laws used to develop wave equation for fluids

1) **Equation of State** – determined by thermodynamic properties
   Relates changes in \( P \) and \( \rho \)
   Dependent upon material (for example, an ideal gas is different from a liquid).
   We can expand the Equation of state into linear and nonlinear terms, however, we will only
   be looking at the linear terms (for now).

2) **Equation of Continuity** – Essentially this is conservation of mass. Relative Motion of fluid in
   a volume causes change in density.

3) **Equation of Motion** – Force Equation – Newton’s 2nd law
   Pressure variations generate a force \( F = P \times \text{Area} \) that causes particle motion

(5.2) Let’s first look at the Equation of State:

An equation of state must relate three physical quantities describing the thermodynamic behavior of
the fluid. For example, the equation of state for a perfect gas is
\[ P = \rho \gamma T \]
where \( P \) is the pressure in Pascals, \( \rho \) is the density (kg/m\(^3\)) and \( T \) is the temperature in Kelvin. If
the gas has high thermal conductivity then any slow compressions of the gas will be isothermic and
\[ \frac{P}{P_0} = \frac{\rho}{\rho_0}. \]
If the thermal conductivity is sufficiently low, the heat conduction during a cycle of the acoustic
disturbance becomes negligible. In this case the condition is considered adiabatic and the relation
between the pressure and density for the perfect gas are:
\[ \frac{P}{P_0} = \left( \frac{\rho}{\rho_0} \right)^\gamma \]
where \( \gamma \) is the ratio of specific heats, \( \frac{C_p}{C_v} \).

The perfect gas is a simple case for an adiabat. Other fluids will have a more complicated
relationship between \( P \) and \( \rho \) under adiabatic expansion. To model this relationship, let expand \( P \) as
a function of \( \rho \) (about \( \rho_0 \)) in a Taylor series:
\[ P = P_0 + \left( \frac{\partial P}{\partial \rho} \right)_{\rho_0} (\rho - \rho_0) + \frac{1}{2} \left( \frac{\partial^2 P}{\partial \rho^2} \right)_{\rho_0} (\rho - \rho_0)^2 + ... \]

The Taylor series shows the fluctuations of \( P \) with \( \rho \). We can rewrite this as:
\[
P = P_0 + A s + \frac{1}{2} B s^2 + \frac{1}{3!} C s^3 + ...
\]
where
\[
A = \rho_0 \left( \frac{\partial P}{\partial \rho} \right)_{\rho_0},
\]
\[
B = \rho_0^2 \left( \frac{\partial^2 P}{\partial \rho^2} \right)_{\rho_0}.
\]

The Taylor series is nonlinear. The nonlinearity of a propagation medium is usually characterized by the ratio of \( B/A \).

We linearize the Taylor series by assuming small fluctuations so that only the lowest order term in \((\rho - \rho_0)\) need be retained. This gives:
\[
p = P - P_0 = A s
\]
where we define the coefficient \( A \) as the adiabatic bulk modulus, \( B \):
\[
A = B = \rho_0 \left( \frac{\partial P}{\partial \rho} \right)_{\rho_0}
\]

Let’s examine the unit for \( B = \rho_0 \left( \frac{\partial P}{\partial \rho} \right)_{\rho_0} \):
- \( P \) : Pascal where \( 1 \text{Pa} = 1 \text{N/m}^2 = 1 \text{kg/s}^2/\text{m} \)
- \( \rho \) : kg/m\(^3\)
- \( \frac{P}{\rho} \rightarrow \frac{m^2}{s^2} \)
- \( \frac{P}{\rho} \rightarrow c^2 \) (speed) (experimentally determined)

so
\[
p = \rho_0 c^2 s = B s
\]
is the Equation of State for linear acoustic waves in fluids (small changes in density \(|s| \ll 1\)).

*************** Example 5.1 ***************

\[
p = B s = \rho_0 c^2 s
\]

From tables: for fresh water @ 20°C: \( \rho_0 = 998 \text{ kg/m}^3 \) and \( c = 1481 \text{ m/s} \)

For \( p = 1 \text{ atm} = 1.0133 \text{ bar} = 1.0133 \times 10^5 \text{ Pa} \)
\[ s = \frac{p - p_0}{\rho_0} = \frac{p}{\rho_0 c^2} = \frac{1.0133 \times 10^5}{(998)(1481)^2} = 4.63 \times 10^{-5} \]

for air @ 20°C: \( p_0 = 1.21 \) kg/m\(^3\) and \( c = 343 \) m/s

\[ s = \frac{1.0133 \times 10^5}{(1.21)(343)^2} = 0.712 \]

1 atm is a huge density fluctuation in air.

(5.3) The Equation of Continuity

Recall this is essentially a statement of conservation of mass.

The book looks at a 3D representation of a fluid particle. We are going to look at a 1D representation and then generalize to 3D.

Cross sectional area \( A \)

\[
\begin{array}{c|c|c|c}
\text{x} & \text{x + }\xi_x (x,t) & \text{x + }\Delta x & \text{x + }\Delta x + \xi_x (x + \Delta x, t) \\
\end{array}
\]

Let’s first consider an undisturbed volume of mass \( = \rho_0 A \Delta x \).

Then, the mass is disturbed (expands) so that the new volume is:

\[
A \left[ x + \Delta x + \xi_x (x + \Delta x, t) - (x + \xi_x (x + \Delta x, t)) \right] = A \left[ \Delta x + \xi_x (x + \Delta x, t) - \xi_x (x + \Delta x, t) \right].
\]

For small \( \Delta x \)

\[
\xi_x (x + \Delta x, t) - \xi_x (x + \Delta x, t) \approx \frac{\partial \xi_x}{\partial x} \Delta x \text{ (approximately)}
\]

giving the new volume

\[ A \Delta x \left( 1 + \frac{\partial \xi_x}{\partial x} \right). \]

Our disturbed density will then be

\[
\rho = \frac{\text{mass}}{\text{volume}} = \frac{\rho_0 A \Delta x}{A \Delta x \left( 1 + \frac{\partial \xi_x}{\partial x} \right)} \rightarrow p_0 = \rho \left( 1 + \frac{\partial \xi_x}{\partial x} \right).
\]
Now, recall that the condensation is:

\[ s = \frac{\rho - \rho_0}{\rho_0} . \]

Solving for the total density gives

\[ \rho = s\rho_0 + \rho_0 . \]

Substituting into our equation above yields

\[ \rho_0 = (s\rho_0 + \rho_0) \left( 1 + \frac{\partial \xi_x}{\partial x} \right) \]

or rearranging

\[ s\rho_0 = -\rho_0 \frac{\partial \xi_x}{\partial x} - s\rho_0 \frac{\partial \xi_x}{\partial x} . \]

If we assume that \( s \) and \( \frac{\partial \xi_x}{\partial x} \) are small so that the second term is negligible (most often the case).

\[ s = -\frac{\partial \xi_x}{\partial x} \]

Notice that the condensation, \( s \), is the fractional change in density. This equation tells us that if the displacement, \( \xi_x \), varies with \( x \) then there is a density change. The minus sign is significant.

If the displacement increases with \( x \) what happens to the density? Why?

If we generalize the equation to 3-D we get

\[ s = -\frac{\partial \xi_x}{\partial x} - \frac{\partial \xi_y}{\partial y} - \frac{\partial \xi_z}{\partial z} \]

or

\[ s = -\left( \frac{\partial}{\partial x} \hat{x} + \frac{\partial}{\partial y} \hat{y} + \frac{\partial}{\partial z} \hat{z} \right) \left( \xi_x \hat{x} + \xi_y \hat{y} + \xi_z \hat{z} \right) \]

\[ s = -\nabla \cdot \xi . \]

If we differentiate with respect to time

\[ \frac{\partial}{\partial t} \left( s = -\nabla \cdot \xi \right) \]

we note that \( \frac{\partial}{\partial t} \left( -\nabla \cdot \xi \right) = -\nabla \frac{\partial \xi}{\partial t} \) and \( \frac{\partial \xi}{\partial t} = \dot{u} \) so

\[ \frac{\partial s}{\partial t} = -\nabla \cdot \ddot{u} . \]

or alternatively if we substitute in for the density we have:

\[ \frac{\partial \rho}{\partial t} = -\rho_0 \nabla \cdot \ddot{u} . \]
(5.4) The Simple Force Equation: Euler’s Equation

Again, let’s consider a small volume of fluid \( dV = dx \, dy \, dz \) that is undergoing a force in the \( x \)-direction. The fluid element is moving with the surrounding fluid. The fluid element has a mass, \( dm \). We will consider the 1D case and then generalize to the 3D case.

The force on the fluid from Newton’s 2\(^{nd}\) law implies:
\[
df = adm.
\]

Now, the pressure, \( P = \frac{\text{force}}{\text{area}} \), and in the figure we see the force is exerted on the cross sectional area, \( dA = dy \, dz \). Looking at the differential force or pressure across the \( dm \) element in the \( x \)-direction.
\[
df_x = \left[ P - \left( P + \frac{\partial P}{\partial x} \, dx \right) \right] dA
\]
\[
df_x = -\frac{\partial P}{\partial x} \, dy
\]

Generalizing to 3 dimensions:
\[
df = df_x \hat{x} + df_y \hat{y} + df_z \hat{z}
\]
\[
df = -\left( \frac{\partial P}{\partial x} \hat{x} + \frac{\partial P}{\partial y} \hat{y} + \frac{\partial P}{\partial z} \hat{z} \right) dv
\]
\[
df = -\nabla P dv
\]

Relating to Newton’s 2\(^{nd}\) Law (3D)
\[
df = \vec{a} \, dm
\]

where
\[
\vec{a} = \frac{du}{dt}.
\]

Recall, there is a difference between
\[
\frac{du}{dt} \quad \text{and} \quad \frac{\partial u}{\partial t}.
\]
\[
\frac{d\mathbf{u}}{dt} = \frac{\partial \mathbf{u}}{\partial x} \frac{dx}{dt} + \frac{\partial \mathbf{u}}{\partial y} \frac{dy}{dt} + \frac{\partial \mathbf{u}}{\partial z} \frac{dz}{dt} + \frac{\partial \mathbf{u}}{\partial t}
\]

or simplifying
\[
\frac{d\mathbf{u}}{dt} = \frac{\partial \mathbf{u}}{\partial x} u_x + \frac{\partial \mathbf{u}}{\partial y} u_y + \frac{\partial \mathbf{u}}{\partial z} u_z + \frac{\partial \mathbf{u}}{\partial t}
\]
\[
\ddot{\mathbf{a}} = \frac{d\mathbf{u}}{dt} = (\mathbf{u} \cdot \nabla) \mathbf{u} + \frac{\partial \mathbf{u}}{\partial t}.
\]

Using the fact that \(dm = \rho dv\) then relating the forces gives
\[
-\nabla P dv = \rho \left[ (\mathbf{u} \cdot \nabla) \mathbf{u} + \frac{\partial \mathbf{u}}{\partial t} \right] dv
\]
\[
-\nabla P = \rho \left[ (\mathbf{u} \cdot \nabla) \mathbf{u} + \frac{\partial \mathbf{u}}{\partial t} \right]
\]

This is the nonlinear, inviscid force equation (viscosity introduced later as a loss mechanism).

To get the linear Euler’s equation we will retain only the 1\(^{st}\) order terms.

1\(^{st}\): \(p = P - P_0\) \(\rightarrow\) \(\nabla p = \nabla P\).

2\(^{nd}\): The particle velocity is assumed small so terms of 2\(^{nd}\) order are negligible giving:
\[
-\nabla p = \rho \frac{\partial \mathbf{u}}{\partial t}
\]

3\(^{rd}\): If we assume that \(|s| < 0.1\) (small) then \(\rho = \rho_0\) giving finally:
\[
-\nabla p = \rho_0 \frac{\partial \mathbf{u}}{\partial t}
\]

(5.5) The Linearized Wave Equation

Summary:
(1) Equation of State (Linearized):
\[
p = B_s = \rho_0 c^2 s
\]
(2) Continuity Equation (Linearized):
\[
\frac{\partial p}{\partial t} = -\rho_0 \nabla \cdot \mathbf{u}
\]
(3) Euler’s Equation (Linearized):
\[
-\nabla p = \rho_0 \frac{\partial \mathbf{u}}{\partial t}
\]

To derive the Nonlinear Wave Equation we first take the derivative of \(s\)

Recall \(s = \frac{\rho - \rho_0}{\rho_0}\)
So that \( \frac{ds}{dt} = \frac{1}{\rho_0} \frac{d\rho}{dt} \) or \( \frac{d\rho}{dt} = \rho_0 \frac{ds}{dt} \).

Substituting this into the Continuity Equation (2) gives
\[
\mathcal{R}_0 \frac{\partial s}{\partial t} = -\mathcal{R}_0 \nabla \cdot \bar{u}
\]
Substituting in the Equation of State (1) yields
\[
\frac{\partial}{\partial t} \left[ \begin{array}{c} p \\ \mathcal{B} \end{array} \right] = -\nabla \cdot \bar{u}
\]
\[
\frac{\partial p}{\partial t} = -\mathcal{B} \nabla \cdot \bar{u} \tag{4}
\]
Taking the derivative of (4) wrt time gives:
\[
\frac{\partial^2 p}{\partial t^2} = -\mathcal{B} \frac{\partial}{\partial t} \nabla \cdot \bar{u} = -\mathcal{B} \nabla \cdot \frac{\partial \bar{u}}{\partial t} \tag{5}
\]
If we take the divergence of Euler’s Equation (3):
\[
\nabla \cdot \left[ \begin{array}{c} \nabla \cdot -\nabla p = \rho_0 \frac{\partial \bar{u}}{\partial t} \\ \end{array} \right]
\]
\[
-\frac{1}{\rho_0} \nabla^2 p = \nabla \cdot \frac{\partial \bar{u}}{\partial t}.
\]
Substituting into (5) gives the result:
\[
\frac{\partial^2 p}{\partial t^2} = \frac{\mathcal{B}}{\rho_0} \nabla^2 p
\]
Using \( \mathcal{B} = \rho_0 c^2 \) gives us the Linearized Wave Equation:
\[
\frac{\partial^2 p}{\partial t^2} = c^2 \nabla^2 p
\]
This is also (in form) the Classical Wave Equation!

The speed of sound is given by: \( c^2 \)

We can also define a velocity potential (similar to EM).

From eq (3), Euler’s equation, we note that the curl of a gradient is zero (\( \nabla \times \nabla f = 0 \)) so:
\[
\nabla \times \left\{ -\nabla p = \rho_0 \frac{\partial \bar{u}}{\partial t} \right\}
\]
\[
-\nabla \times \nabla p = 0 = \rho_0 \frac{\partial \nabla \times \bar{u}}{\partial t}
\]
which implies
\[
\nabla \times \bar{u} = 0.
\]
This means that the particle velocity can be expressed as the gradient of a scalar function:
\[
\bar{u} = \nabla \Phi.
\]
Substituting back into the Euler’s equation gives:
\[-\nabla p = \rho_0 \frac{\partial \nabla \Phi}{\partial t}\]
or the relation between the pressure and the velocity potential is:
\[p = -\rho_0 \frac{\partial \Phi}{\partial t}.\]

The velocity potential, $\Phi$, can also be shown to satisfy the wave equation.

(5.6) Speed of Sound in Fluids

Let’s evaluate the Equation of State:

\[B = \rho_0 \left( \frac{\partial P}{\partial P} \right)_{\rho_0} = \rho_0 c^2 \quad \text{so that} \quad c^2 = \left( \frac{\partial P}{\partial \rho} \right)_{\rho_0}.
\]

It is necessary to know how temperature, $T$, behaves in an acoustic wave. Newton applied Boyle’s Law: $PV = \text{constant}$ when $T$ is held constant. This means that heat is conducted from one region to another so that temperature does not change. This is known as an ISOTHERMAL PROCESS, that is, $PV = \text{constant}$ at constant $T$ or $\frac{P}{\rho} = \text{constant}$ at constant $T$.

Consider: For an isothermal process,

\[\frac{P}{\rho_0} = \frac{P}{\rho} \rightarrow \frac{P}{\rho} = \frac{P}{\rho_0}.
\]

Relating this back to the speed of sound,

\[c^2 = \left( \frac{\partial P}{\partial \rho} \right)_{\rho_0} = \frac{\partial}{\partial \rho} \left( \frac{P}{\rho_0} \right)_{\rho_0} = \frac{P}{\rho_0}
\]

Therefore, $c = \sqrt{\frac{P}{\rho_0}}$

For air at STP where

$P_o = 1\text{atm} = 1.013 \times 10^5 \text{Pa} = 101.3\text{kPa} \quad (1\text{Pa} = 1\text{N} \text{ / m}^2)$

$\rho_o = 1.293\text{kg/m}^3$

The propagation speed assuming an isothermal process is

$c = \sqrt{\frac{P}{\rho_o}} = \sqrt{\frac{1.013 \times 10^5 \text{Pa}}{1.293\text{kg/m}^3}} = 279.9\text{m/s}$

But, at STP, the actual propagation speed in air is 331.6 m/s! Let’s examine the assumptions. Sound in the audio and ultrasonic frequency ranges is an adiabatic process, that is, there is insufficient time for heat to flow between compressed and rarefied regions. If heat has sufficient time to flow between compressed and rarefied regions, then the process maintains approximately the same temperature, and is therefore an isothermal process. Acoustic waves propagating in air do
Consider the ADIABATIC GAS LAW, that is, \( PV^\gamma = \text{constant} \), or \( \frac{P}{\rho^\gamma} = \text{constant} \) where \( \gamma \) is the ratio of specific heats, that is, \( \gamma = \frac{c_p}{c_v} \).

Consider:

\[
\frac{P_o}{\rho_o^\gamma} = \frac{P}{\rho^\gamma} \to P = \frac{\rho^\gamma P_o}{\rho_o^\gamma} \quad \text{(Eq. A9.23)}
\]

Relating this back to the speed of sound:

\[
c^2 = \left( \frac{\partial P}{\partial \rho} \right)_o = \frac{\partial}{\partial \rho} \left( \frac{\rho^\gamma P_o}{\rho_o^\gamma} \right)_o = \frac{\gamma P_o}{\rho_o}
\]

Therefore, \( c = \sqrt{\frac{\gamma P_o}{\rho_o}} \)

For air at STP where

\( P_o = 1 \text{ atm} = 1.013 \times 10^5 \text{ Pa} = 101.3 \text{kPa} \) (1 Pa = 1 N / m\(^2\))

\( \rho_o = 1.293 \text{ kg/m}^3 \)

\( \gamma = 1.402 \)

Thus, the propagation speed assuming an adiabatic process is

\[
c = \sqrt{\frac{\gamma P_o}{\rho_o}} = \sqrt{\frac{(1.402)(1.013 \times 10^5 \text{ Pa})}{1.293 \text{ kg/m}^3}} = 331.4 \text{ m/s} \quad \text{(what we actually measure)}
\]

In general, for a gas \( c = \sqrt{\frac{\gamma P_o}{\rho_o}} \) and, for a liquid \( c = \sqrt{\frac{\gamma B_T}{\rho_o}} = \sqrt{\frac{B_A}{\rho_o}} \) where

\( B_T = \) isothermal bulk modulus

\( B_A = \) adiabatic bulk modulus, that is \( B_A = \gamma B_T \)

From Appendix A10 for fresh water at 20°C

\( B_T = 2.18 \times 10^9 \text{ Pa} = 2.18 \text{ GPa} \)

\( \rho_o = 998 \text{ kg/m}^3 \)

\( \gamma = 1.004 \)

Thus, the propagation speed assuming an adiabatic process is
\[ \gamma = \frac{d + 2}{d - 5} = \frac{7}{5} = 1.4 \]

\[ c = \sqrt{\gamma r T_k} = \sqrt{(1.4 \left( 287.1 \frac{J}{kg \cdot ^o K} \right) \left( 273.16^o K \right)} = 331.4 \text{ m/s} \]

Note unit: \[ \sqrt{\frac{J}{kg}} = \sqrt{\frac{N \cdot m}{kg}} = \sqrt{\frac{(kg \cdot m^2/s^2) \cdot m}{kg}} = \sqrt{\frac{m^2}{s^2}} = \frac{m}{s} \]

In solids, two types of waves can propagate, that is, longitudinal and shear, each having a different propagation speed:
\[ c_L = \sqrt{\frac{Y(1-\sigma)}{\rho_o(1+\sigma)(1-2\sigma)}} \]
\[ c_S = \sqrt{\frac{Y}{2\rho_o(1+\sigma)}} \]

where \( c_L > c_S \)

where (see Appendix A10)
\( Y \) = Young’s modulus
\( \sigma \) = Poisson’s ratio

Density and propagation speed ranges are

Gases:
\( \rho_o \approx 1 \text{ kg/m}^3 \)
\( c_o \approx 100 - 1,000 \text{ m/s} \)

Liquids:
\( \rho_o \approx 1,000 \text{ kg/m}^3 \)
\( c_o \approx 1,000 - 2,000 \text{ m/s} \)

Solids
\( \rho_o \approx 2,000 - 10,000 \text{ kg/m}^3 \)
\( c_L \approx 2,000 - 10,000 \text{ m/s (Longitudinal or Bulk)} \)
\( c_S \approx 1,000 - 5,000 \text{ m/s (Shear or Bar)} \)

Let’s calculate the acoustic pressure in a gas for a typical acoustic wave. Assume the solution for the 1D wave equation in terms of the particle displacement.

\[ \frac{\partial^2 \xi}{\partial t^2} = c^2 \frac{\partial^2 \xi}{\partial x^2} \]

If the acoustic wave is traveling in one direction then we have a solution of the form:

\( \xi(x,t) = \xi_0 \cos(\omega t - kx) \)

where \( k = \frac{\omega}{c} = \frac{2\pi}{\lambda} \) is the wave number (radians per meter, 1/m)
\( \omega = 2\pi f \) is the angular frequency (radians per second, 1/s)
\( c \) is the propagation speed (m/s).

You may recall from our consideration of the continuity equation that we came up with a relation between the condensation, \( s \), and the particle displacement.

\[ s = -\frac{\partial \xi}{\partial x} \]

(in one direction)

By combining the Equation of State with the equation above, we can obtain the acoustic pressure in terms of the particle displacement:
The instantaneous condensation (from the solution to the 1D wave equation) is
\[ \frac{\partial \xi}{\partial x} = -\xi \cos(\omega t - kx) \]
and the instantaneous acoustic pressure is
\[ p(x, t) = \rho_o c^2 \xi \sin(\omega t - kx) \]
\[ = -\rho_o c^2 \xi_o \omega \sin(\omega t - kx) = p_o \sin(\omega t - kx) \]

Remember this one!

In \( p(x, t) = -\rho_o c^2 \xi \omega \sin(\omega t - kx) = p_o \sin(\omega t - kx) \), \( p_o \) is the amplitude acoustic pressure, and the magnitude of the amplitude acoustic pressure is:
\[ |p_o| = \rho_o c \xi_o \]

However, most of the time, the absolute brackets are omitted when representing the magnitude of the amplitude acoustic pressure (phase is incorporated into the argument).

So, what does this mean in real terms:

*************************** Example 5.2 ***************************

If an individual speaks (in air at 20°C) at a Sound Pressure Level (SPL) of 70 dB, at a frequency of 1 kHz, then what are the magnitudes of the amplitude acoustic pressure and amplitude particle displacement?

ANSWER: Sound Pressure Level (see Eq 5.12.2) is defined as
\[ \text{SPL} = 20 \log_{10} \left( \frac{p_o}{p_{\text{ref}}} \right) \]
where \( p_o \) is the peak (or rms) amplitude pressure and \( p_{\text{ref}} \) is the peak (or rms) reference amplitude pressure (“rms” is also referred to as “effective”). Note that the numerator and denominator must be either peak or rms, not mixed. The airborne pressure reference (see Table 5.12.1) is 28.9 µPa (peak) or 20 µPa (rms); this is a SPL of 0 dB. Therefore,
\[ 70 = 20 \log_{10} \left( \frac{p_o}{p_{\text{ref}}} \right), \quad \left| p_o \right| = 10^{70/20} = 3162.3, \]
\[ \left| p_o \right| = (3162.3) (28.9 \mu Pa) = 0.0914 \text{ Pa (peak)} \]
\[ \text{or} \left| p_o \right| = (3162.3) (20 \mu Pa) = 0.0632 \text{ Pa (rms)}. \]

That means that the particle displacement is:
\[
\xi_o = \frac{|p_o|}{\rho_o c \omega} = \frac{0.0914 \text{ Pa}}{\left(1.21 \text{ kg} / \text{m}^3\right) \left(343 \text{ m} / \text{s}\right)(2\pi \times 1000 \text{ r/s})} = 35 \text{ nm (peak)}. \]

Note that the reference amplitude acoustic pressure (peak) at 1 kHz is 0.11 Å (1 Å = 0.1 nm).

\[\xi(x,t) = \xi_o \cos(\omega t - kx).\]

The instantaneous particle velocity is
\[u(x,t) = \frac{\partial \xi(x,t)}{\partial t} = -\omega \xi_o \sin(\omega t - kx)\]

The instantaneous particle acceleration is
\[a(x,t) = \frac{\partial u(x,t)}{\partial t} = -\omega^2 \xi_o \cos(\omega t - kx)\]

The instantaneous condensation is
\[s(x,t) = -\frac{\partial \xi(x,t)}{\partial x} = -k \xi_o \sin(\omega t - kx).\]

The respective magnitude expressions are (these are useful to know!):
\[u_o = \omega \xi_o = \frac{|p_o|}{\rho_o c}\]
\[a_o = \omega u_o = \omega^2 \xi_o = \frac{\omega |p_o|}{\rho_o c}\]
\[s_o = k \xi_o = \frac{\omega \xi_o}{c} = \frac{u_o}{c} = \frac{|p_o|}{\rho_o c^2}\]

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\textbf{Example 5.2}********************************************************************

If an individual speaks (in air at 20°C) at a Sound Pressure Level (SPL) of 70 dB, at a frequency of 1 kHz, then what are the magnitudes of the amplitude particle velocity, amplitude particle acceleration and amplitude condensation?

ANSWER: Using information from the previous example, magnitudes (peak values) of the amplitude particle velocity is \(2.20 \times 10^{-4} \text{ m/s}\), amplitude particle acceleration is \(1.38 \text{ m/s}^2\) and amplitude condensation is \(6.72 \times 10^{-7}\). Small…

A significant parameter in shock wave theory is the \textit{Mach number} (see Problem 5.7.1 in Kinsler et al). Based on the parameters introduced already, the \textit{Mach number} is defined as \(M = \frac{u_o}{c}\). Note how this compares to the magnitude of condensation: \(s_o = k \xi_o = \frac{\omega \xi_o}{c} = \frac{u_o}{c} = \frac{|p_o|}{\rho_o c^2}\)